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High-fidelity simulations of turbulent compressible flows in aerodynamics: some typical applications with ONERA CFD codes

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MUMPS User Days, Sorbonne University, Paris June 22-23, 2023

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Outline

- Scientific challenge
- Physical modeling and numerics
- Some typical applications
- Krylov iterative solvers for large-scale systems
- Ongoing research activities
- Concluding remarks



Scientific challenge

- Industrial demand for accurate solutions of turbulent compressible flows in aerodynamics
 - Flow features: vorticity, turbulence,...
 - Quantities of interest: lift, drag,...
- High-fidelity simulations often imply
 - Large number of discretization elements to tackle complexity (physics, geometry)
 - A physical modeling of more and more complex phenomena
 - And as a result ... increasingly large and ill-conditioned linear systems !
- Robust and efficient parallel strategies for linear systems are mandatory
 - Solutions must be delivered at a prescribed tolerance if required
- Some properties of the corresponding matrices
 - Matrices are real non-symmetric (values) or complex non-hermitian
 - A block-wise structure and a symmetric pattern



Scientific challenge

Places where linear algebra is involved

- Dealing with the linearized equations (Jacobian-vector products)
 - Solve Newton (or pseudo-transient) algorithm
 - Shape optimization
 - Global stability analysis
 - ...
- Dealing with adjoint equations (Transposed Jacobian-vector products)
 - Shape optimization
 - Goal-oriented mesh adaptation
 - Resolvent analysis
 - Uncertainty quantification
 - Sensitivity



. . .

Physical modeling and numerics – CFD

$$\begin{cases} \frac{\partial q}{\partial t} + \nabla \cdot F(q) = S(q, \mathbf{x}) \\ q(t = 0) = q_0 \\ q(\mathbf{x} \in \partial \Omega) = q_{BC} \end{cases}$$

where

- q: a vector of conserved quantities,
- *x*: a vector defining the position in space,
- *F*: a tensor of conservative fluxes,
- *S*: a vector of source terms.

Very large number of DoF

... from 10⁵ (simple 2D flows) up to 10¹⁰ (3D flows) !



Physical modeling and numerics – CFD

Most of the CFD computations require fixed point evaluation

R(q,X)=0

Implicit discrete Navier-Stokes equations

$$\left(\frac{\Omega}{\lambda\Delta t}I - \frac{\partial R}{\partial q}\right)\Delta q = R(q, X)$$

where

X: the mesh,

 Ω : a mass matrix,

 Δt : the time step,

 λ : the CFL number,

and the explicit residual R supposed C^1

$$R(q, X) = -\nabla \cdot F(q) + S(q, X)$$



$q'(\mathbf{x},t) = \hat{q}(\mathbf{x})e^{\nu t}$ Figure III.12: Real part of streamwise (a) and cross-stream (b) velocity perturbation of the direct unstable mode at Re = 47. Solid lines indicate iso-contours at $\Re(\hat{u}_x) \pm 0.1$ and $\Re(\hat{u}_y) \pm 0.1$.

(b)

envalue problem
$$A_b q$$

$$A_b \; \hat{q} = \sigma \hat{q}$$
 , with $A_b = rac{\partial R}{\partial q} |_b$

(a)

For each couple
$$(\sigma_i, \hat{q}_i)$$
 gives

 \hat{q}_i : the spatial structure of the i^{th} mode *Real*(σ_i): its amplification rate (asymptotically unstable if >0)

 $Im(\sigma_i)$: its angular frequency

* V. Theofilis. *Progress in aerospace sciences*, 39(4):249–315, 2003.





Flow is decompsed as : $q = q_b + q'$

Linearized equations

Searching solution as

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 $\frac{\partial q'}{\partial t} = \frac{\partial R}{\partial q} |_{b} q'$

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Physical modeling and numerics – Stability Analysis

Adjoint global stability analysis (*, **)

The adjoint operator A^* of A is defined relatively to a given scalar product $\langle \cdot, \cdot \rangle_Q$

$$\forall x, y: \qquad \langle x, Ay \rangle_Q = \langle xA^*, y \rangle_Q \implies A^* = Q^{-1}A^T Q$$

Each eigen mode (σ_i, \hat{q}_i) has its related adjoint one $(\overline{\sigma_i}, \hat{q}_i^*)$.

Useful to study receptivity of the direct mode.

** F. Giannetti and P. Luchini. Structural sensitivity of the first instability of the cylinder wake. Journal of Fluid Mechanics, 581, 2007.



^{*} D. Sipp, O. Marquet, P. Meliga, and A. Barbagallo. *Dynamics and control of global instabilities in open-flows: a linearized approach.* Applied Mechanics Reviews, 63(3), 2010.

Physical modeling and numerics – Stability Analysis

Resolvent analysis for amplificator flows as the flat plate (*,**)

Due to non-normality of A, some globally stable flows may be exposed to instabilities that can grow and break symmetries. The most amplified one can be found by applying a forcing ϕ on linearized equations

$$\frac{\partial q'}{\partial t} = Aq' + \phi$$

Fourier transform: $i\omega t \hat{q} = A\hat{q} + \hat{\phi} e^{i\omega t} \iff \hat{q} = J \hat{\phi}$ with $J = (i\omega I - A)^{-1}$

Searching the maximum gain: $\eta^2(\omega) = \sup\left(\frac{\langle \hat{q}, \hat{q} \rangle_{Q_1}}{\langle \hat{\phi}, \hat{\phi} \rangle_{Q_2}}\right) = \sup\left(\frac{\langle J \hat{\phi}, J \hat{\phi} \rangle_{Q_1}}{\langle \hat{\phi}, \hat{\phi} \rangle_{Q_2}}\right)$

Equivalent to solve the following hermitian EVP: $\int J^H Q_1 J \hat{\phi} = \eta^2 Q_2 \hat{\phi}$

^{*} L.N. Trefethen, A.E. Trefethen, S.C. Reddy, T.A. Driscoll. Hydrodynamic stability without eigenvalues, Science 261, 578–584, 1993 ** D. Sipp. O. Marquet. Characterization of noise amplifiers with global singular modes: the case of the leading-edge flat-plate boundary layer. Theor. Comput. Fluid Dyn. 27, 617-635, 2013.



Physical modeling and numerics – Stability Analysis

Usual way to perform Stability Analysis

Only a few part of the spectrum is exhibed.

EVP are solved by mean of iterative solver such as the Krylov-Schur (*) solver, an Arnoldi based method which iteratively converges towards eigenvalues of largest magnitudes.

Global modes (Shift and Invert (**)): $(\mathbf{A} - s\mathbf{I})^{-1}\hat{q} = \tilde{\sigma}\hat{q}$ and $\sigma = \tilde{\sigma}^{-1} + s$

Resolvent: $J^H Q_1 J \hat{\phi} = \eta^2 Q_2 \hat{\phi}$ or $J Q_2^{-1} J^H Q_1 \hat{q} = \eta^2 \hat{q}$, with $J = (i\omega I - A)^{-1}$

With enough memory, the best practice is the LU factorisation for each operator All operators are obtained by mean of A. D. with Tapenade (***)

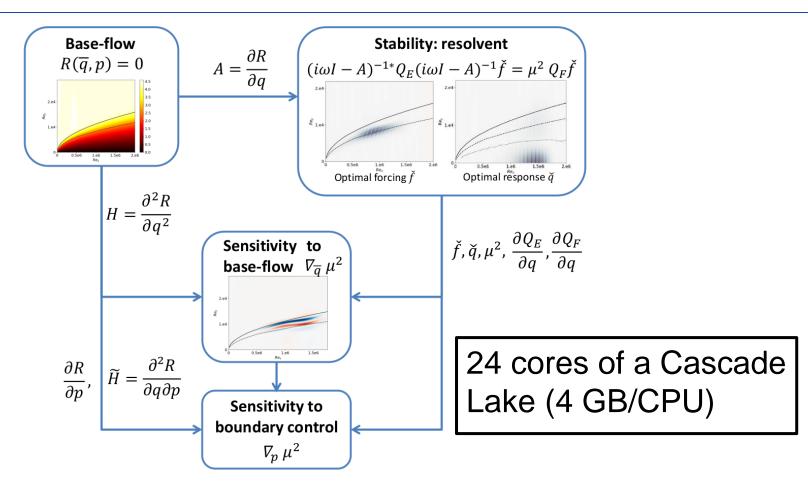
^{***} L. Hascoët, and V. Pascual. The Tapenade automatic differentiation tool : Principles, model, and specification, ACM Trans. Math. Softw. 39(3) : 20 (2013)



^{*} G. Stewart. A Krylov-Schur Algorithm for Large Eigenproblems. SIMAX, 23(3):601-614, 2002.

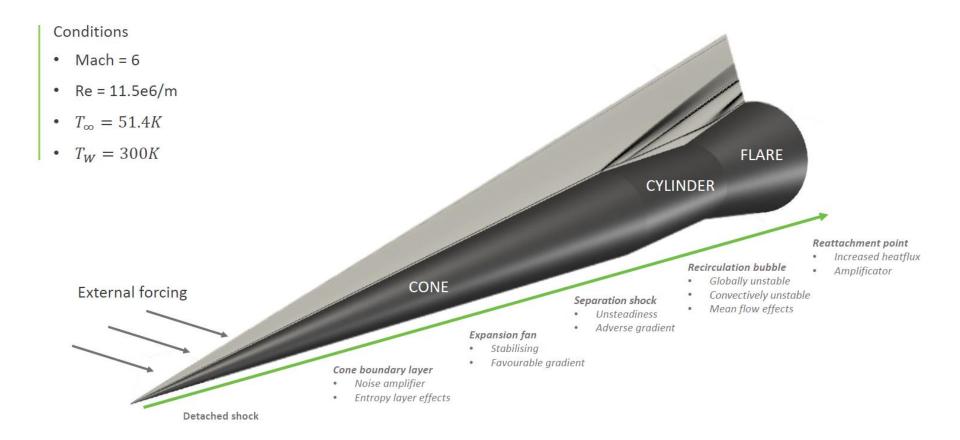
^{**} K. N. Christodoulou and L. E. Scriven. *Finding leading modes of a viscous free surface flow: An asymmetric generalized eigenproblem.* J Sci Comput, 3(4):355–406,1988.

Application to flow over flate plate at Mach=4.5 A. Poulain (ONERA/DAAA) (*, **) ; NDoF ~ 10⁶

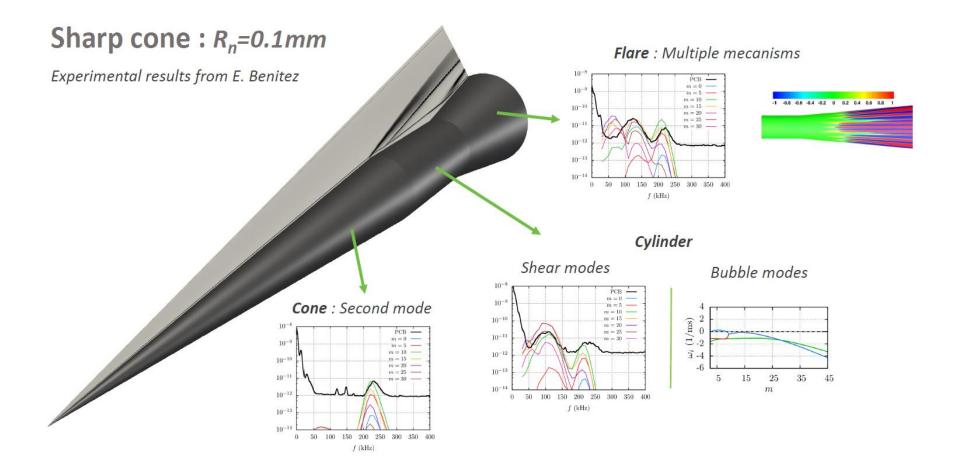


* A. Poulain, C. Content, D. Sipp, G. Rigas, E. Garnier. *BROADCAST: A high-order compressible CFD toolbox for stability and sensitivity using Algorithmic Differentiation*. Computer Physics Communications 283, 108557 (2023). ** A. Poulain, C. Content, D. Sipp, G. Rigas, E. Garnier. *Adjoint-based linear sensitivity of a hypersonic boundary layer to steady wall blowing-suction/heating-cooling*, arXiv 13 June 2023.



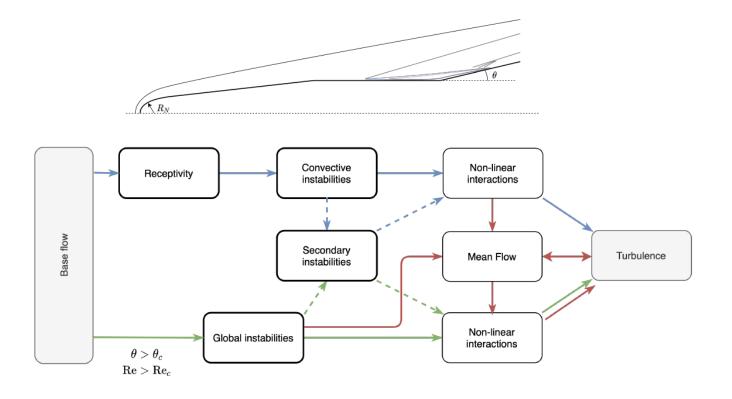




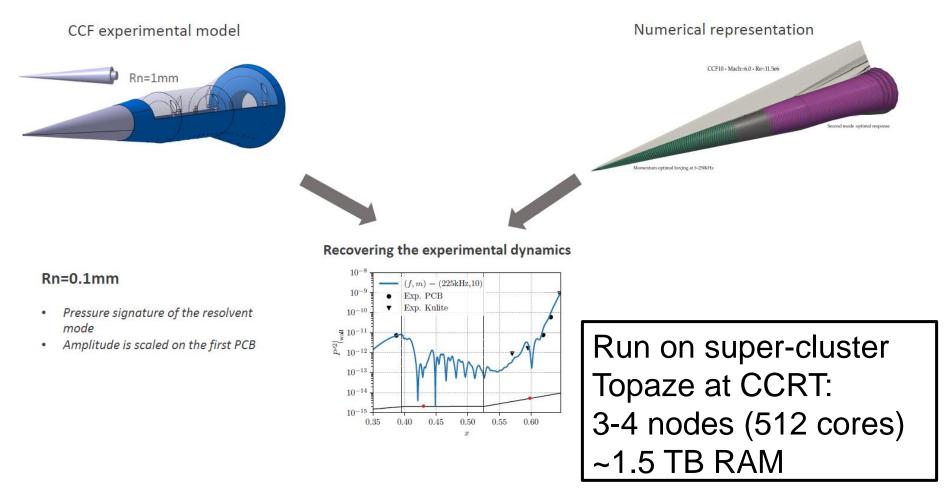








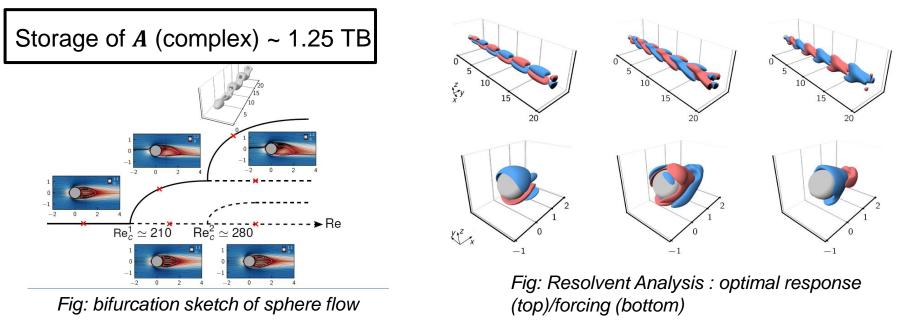






Scaling up toward industrial applications on unstructured mesh (*)

- A 3D Navier-Stokes example: N_{eq} = 5, N_{cell} = 25 M → NDoF = 125 M
- ONERA Cluster with Intel Cascade Lake nodes (4 GB/CPU)
- Number of non-zero values of the matrix: $NNZ(A) \simeq stencil \times N_{eq} \times NDoF$
- Finite Volume Spatial Discretization of Order 2 (Stencil \simeq 125)



* V. Fer. Scale up of efficient global stability tools in order to characterize specific turbomachineries phenomenons, PhD Thesis, 2022



Scaling up toward industrial applications applications on unstructured mesh (*)

Method	Estimation	Memory	NCPU
LU	$\left(\frac{NNZ(A)}{7}\right)^{4/3}$	~1000 TB	>250000
KM-ILU(k)	$\gamma(k) \times NNZ(A) + n_{KM} \times N_{DOF}$	~ 20 TB	~5000

- Memory requirement of direct methods is still a bottleneck for industrial cases
- Krylov iterative Methods (KM) overcome that point
- But the preconditioning strategy becomes the key issue (***)
 - Classic user parameters: $n_{KM} = 120$, k = 3 ($\gamma(3) = 3$)

V. Fer. Scale up of efficient global stability tools in order to characterize specific turbomachineries phenomenons, PhD Thesis, 2022
J.Y. L'Excellent, Multifrontal Methods: Parallelism, Memory Usage and Numerical Aspects. Hdr, 2012.

*** N. Guilbert. Amélioration de l'inversion de grands systèmes creux pour la simulation numérique en mécanique des fluides. 2021.



• We are looking for **robust** and **efficient parallel** iterative solvers

Krylov iterative solvers for large-scale systems

- Evaluations of several numerical algorithms
 - Deflation techniques GCRO-DR
 - Flexible preconditioning operator FGCRO-DR
 - Mixed-precision algorithms
 - Restricted Additive Schwarz preconditioner

[Parks, de Sturler et al. '06]

[Carvalho, Gratton et al., '11]

[Baboulin et al. '09] [Arioli, Duff, '09]

[Cai, Sarkis, '99]

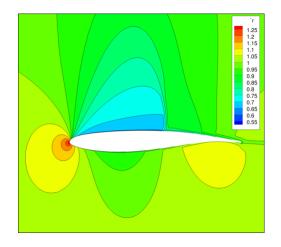
Baseline strategy if accurate solutions are required

- $FGCRO-DR(m_{outer}, k, \varepsilon_{outer} = 10^{-9})$ • $GMRES(m_{inner}, \varepsilon_{inner} = 0.5)$ \Box Restricted Additive Schwarz \bullet P = Block-ILU(0) A_{DP} global A_{SP} global Domain coupling Precond P_{SP} local



Krylov iterative solvers for large-scale systems

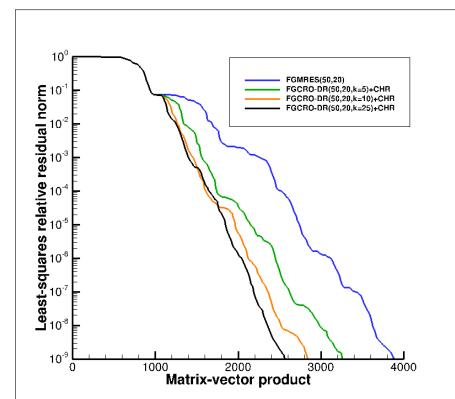
Adjoint solutions with Krylov subspace recycling



OAT15A airfoil

2D compressible (generic) RANS equations Turbulent transonic flow Aerodynamic shape optimization problem: Minimization of the drag coefficient (only *p* contribution)

DG(O4) ; *Aghora* DG code (*) *N* ~ 3.2 M ; *NNZ* ~ 802 M 16 MPI ; Intel Broadwell ; Worst case ~ 300 s



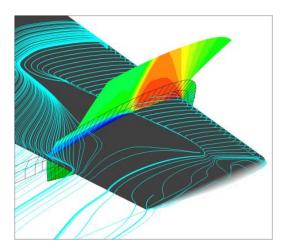
Benefits of recycling varying number k of vectors (CHR)

* F. Renac et al. *Aghora: A High-Order DG Solver for Turbulent Flow Simulations.* IDIHOM: Industrialization of High-Order Methods, Springer book, 2015. This work is supported by the French project DGAC/LAMA (Direction Générale de l'Aviation Civile) and by the European project NextSim.



Krylov iterative solvers for large-scale systems

Adjoint solutions with Krylov subspace recycling

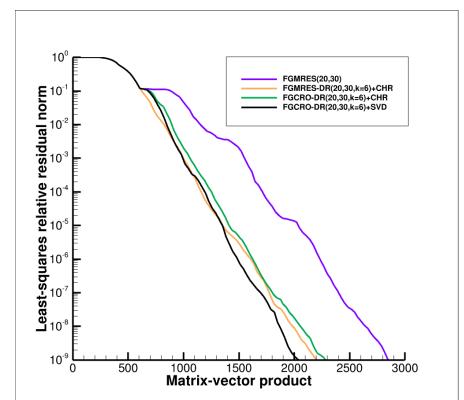


ONERA M6 wing

3D compressible (generic) RANS equations Turbulent transonic flow Aerodynamic shape optimization problem:

Minimization of the drag coefficient (only p contribution)

DG(O4) ; *Aghora* DG code (*) *N* ~ 20 M ; *NNZ* ~ 13 B 176 MPI ; Intel Skylake ; Worst case ~ 420 s



Gains of recycling varying solvers and vector type (CHR, SVD)

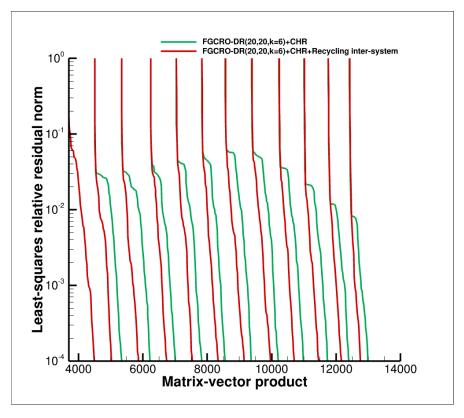
* F. Renac et al. *Aghora: A High-Order DG Solver for Turbulent Flow Simulations.* IDIHOM: Industrialization of High-Order Methods, Springer, 2015. This work is supported by the French project DGAC/LAMA (Direction Générale de l'Aviation Civile) and by the European project NextSim.



Ongoing research activities

Gains of recycling between consecutive systems

- Strategies to select information
 - When to trigger inter-system recycling
 - Type and quality of the vectors



OAT15A airfoil

2D compressible (generic) RANS equations Turbulent transonic flow Sequence of systems from steady-state calculations

DG(O3) ; *Aghora* DG code (*) *N* ~ 2 M ; *NNZ* ~ 288 M 16 MPI ; Intel Broadwell

Recycling starts at the end of the 11th up to the 21th

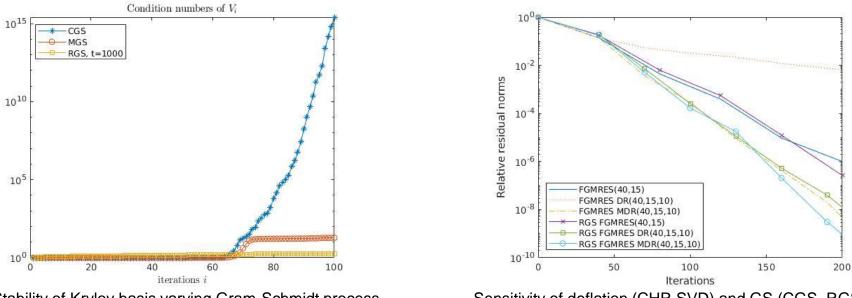
* F. Renac et al. *Aghora: A High-Order DG Solver for Turbulent Flow Simulations*. IDIHOM: Industrialization of High-Order Methods, Springer book, 2015. This work is supported by the French project DGAC/LAMA (Direction Générale de l'Aviation Civile) and by the European project NextSim.



Ongoing research activities

Randomized Flexible GMRES with Deflated Restarting*

- LS89 test-case: subsonic flow, steady problem (FV(02), RANS, SA-negative)
 - Matrix characteristics: N = 115,368 ; NNZ ~ 6 M ; cond(A) ~ 10^{14}
 - Preconditioning operator: GMRES + RAS



Stability of Krylov basis varying Gram-Schmidt process

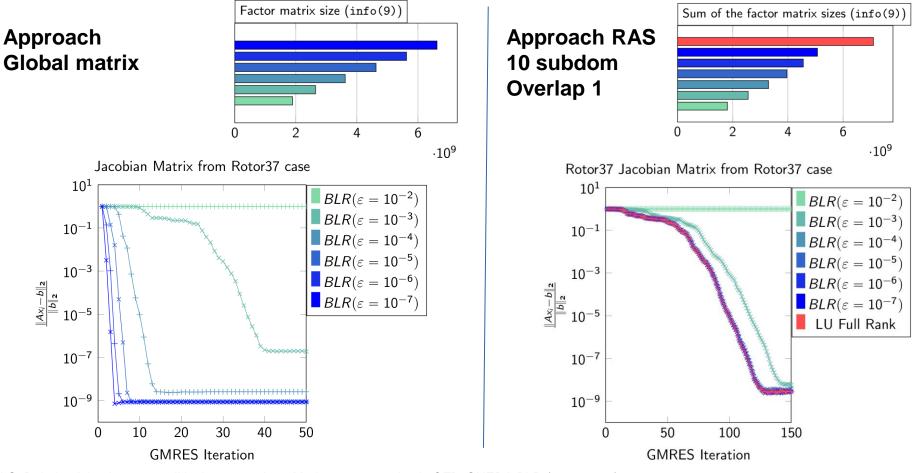
Sensitivity of deflation (CHR,SVD) and GS (CGS, RGS)

* Y. Jang, L. Grigori, E. Martin, C. Content. *Randomized Flexible GMRES with Deflated Restarting*, 2023, hal-04072873. * **This work is funded by DGAC (Direction Générale de l'Aviation Civile) in the frame of the SONICE project.**



Ongoing research activities

MUMPS-BLR preconditioner for a global strategy with memory constraint



* S. Dubois. Adaptive preconditioning strategies with data compression in CFD. ONERA PhD (2022-2025).



Concluding remarks

- Direct methods are used as long as the memory limitation is not reached
- Flexible solvers with Krylov subspace recycling are a promising alternative
 - Capability to address larger problem sizes with robustness/efficiency
 - Significant gains are observed on tough problems
 - Random sketching techniques offer a better numerical stability of Krylov basis
 - Hybrid direct-iterative solvers are of main concern
 - But calibration rules to leverage costs are still needed
- Convergence to steady-state of stiff problems remains problematic
 - Limitations of first-level preconditioner (numerical efficiency / memory cost)
 - Data compression: MUMPS BLR feature, mixed-precision algorithms...
 - Coupling between domains plays a significant role
 - One-level RAS preconditioner is not enough
 - · Coarse space corrections might be explored
 - Parallel scalability ?



Thank you for your attention ! Any question or remark ?

